



# **XLS-1** series

## Compact and precise linear piezo stage

The XLS-1 series are precise linear stages driven by an ultrasonic piezo motor. These stages combine high-speed positioning with nanometre precision. Xeryon's ultrasonic piezo motor ensures you a long lifetime, noiseless and vibration-free operation. In addition, the self-locking piezo motor holds the position of the stage when powered off. The reduced heat dissipation leads to a very stable

nano-positioning system. The XLS-1 is used in metrology applications, e.g. for part alignment or sample manipulation. The XLS-1 series is available in different lengths and are easily stacked into an XY-assembly. All stages can be equipped with a short cage to increase the stroke.

#### **Key features**

drive principle	patented Crossfixx™ ultrasonic piezo technology
bearings	precision crossed-roller
lifetime distance	> 1000 km / typ. 20 million cycles
control principle	closed-loop or open-loop position control
input voltage	48 V

#### Model code structure

ctoro	stage	encoder	optional					
stage type	length (mm)	resolution (nm)	vacuum compatibility	low- or non-magnetic bearings	short cage for increased stroke			
		-OPEN						
		-1250						
	-30	-312		-LM / -NM				
		-78			-SC			
		-5						
		-1						
XLS-1	-40		-HV (10 <sup>-6</sup> mbar) -UHV (10 <sup>-9</sup> mbar)					
	-50		J (10 111241)					
	-60							
	-70	same as for XLS-1-30						
	-80							
	-100							
	-120	1						

#### **Environmental compatibility**

temperature range	-30°C to +70°C
humidity range	20% to 90% RH (non-condensing)
heat dissipation (motor only)	< 1 W
mounting surface flatness	< flatness specification of stage
internal operation voltage	< 48 V

## **Motion performance**

				XLS-1 all lengths						tole-	
	resolution			-OPEN	-1250	-312	-78	-5	-1	1	rance
		type	NA <sup>1</sup>	optical, incremental							
DER		grating period	NA <sup>1</sup>	79	9.8		20		μm		
ENCODER		resolution		NA <sup>1</sup>	1250	312	78	5	1	nm	
ω		index		NA <sup>1</sup>		1	per full stro	oke			
		accuracy	NA <sup>1</sup>	± 10	± 5		± 1		μm	typ.	
	positioning	resolution = min. step size = min. incremental motion (MIM)	50000²	1250	350	80	25		nm	typ.	
	ositi	unidirectional repeatability		± 50000 <sup>2</sup>	± 1250	± 350	± 80	± 25		nm	typ.
	ď	bidirectional repeatability			± 2500	± 700	± 160	± 50		nm	typ.
		max. speed	1000	200 150 25		25	mm/s	typ.			
ЭË		min. speed		5000 <sup>3</sup>	5 2 1		1	μm/s	typ.		
STAGE	_	stability (at typical speed of 10 mm/s)		± 10		± 1				%	typ.
0,	peeds	point-to-point positioning time for a 1 mm step <sup>4</sup>	0 g load 100 g load	NA		.0 5	60 100		50 00	msec msec	typ.
		point-to-point positioning time	10 mm 1 mm 100 μm	NA	4	00 0 0	250 60 50	1:	00 50 0	msec. msec. msec.	typ.
	operation duty cycle (for -HV/-UHV only)					5( 12				% sec	max. max.

<sup>&</sup>lt;sup>1</sup> a closed-loop control can be achieved by connecting an external position encoder to the controller

Note: a detailed description of the technical terms used in this datasheet can be found on the Terminology page of our website.

## **Mechanical properties**

		XLS-1 -30	XLS-1 -40	XLS-1 -50	XLS-1 -60	XLS-1 -70	XLS-1 -80	XLS-1 -100	XLS-1 -120	unit	tole- rance
	length	30	40	50	60	70	80	100	120		
dimensions	width		34							mm	± 0.1
	height		13								
stroke/	standard cage	10	25	30	40	45	50	75	100	mm	. 0.1
travel range	short cage (-SC)	25	30	38	48	52	69	85	109		± 0.1
max. accelera	max. acceleration		45	35	30	25	20	15	10	m/s <sup>2</sup>	typ.
mass (w/o co	mass (w/o connector)		50	63	76	88	105	126	151	g	± 5%
load capacity	(payload limitation)	0.5							kg	max.	
	vertical	237	396	475	633	712	792	990	1188	NI	
load capacity*	lateral	237	396	475	633	712	792	990	1188	N	
(bearing	tilt around pitch axis	1.13	1.50	1.88	2.25	2.63	3.00	3.75	4.50	Nm	max.
force limitation)	tilt around yaw axis	1.13	1.50	1.88	2.25	2.63	3.00	3.75	4.50		
	tilt around roll axis	3.02	5.05	6.06	8.07	9.08	10.10	12.62	15.15		
driving force		1							N	min.	
holding force		1						N	min.		
passive holding stiffness		0.5						N/µm	typ.		

<sup>&</sup>lt;sup>2</sup> when using stage in burst mode (50µs bursts)

<sup>&</sup>lt;sup>3</sup> lower average speeds can be achieved when using burst mode

<sup>&</sup>lt;sup>4</sup> settling within bidirectional repeatability range

stage material slider/base bearings		aluminium stainless steel		
cable length**		1.5	m	± 0.1
connector (stage to controller)		1x 15-pin D-sub HD male (standard) 1x 15-pin D-sub female (-HV)		

<sup>\*</sup> valid for stages with standard cage

#### **Error motion**

		XLS- length 30		XLS length 80			
resolution		-open -1250 -312	-78 -5 -1	-open -1250 -312	-78 -5 -1	unit	tolerance
	straightness	± 5	± 1	± 10	± 2	μm	max.
	flatness	± 5	± 1	± 10	± 2	μm	max.
error motion	pitch	120 25	24 5	120 25	24 5	µrad arcsec	max.
error	roll	120 25	24 5	120 25	24 5	µrad arcsec	max.
	yaw	60 12.5	12 2.5	60 12.5	12 2.5	µrad arcsec	max.

### Controller/software

The XLS-1 series linear stages are compatible with all Xeryon controllers. Controlling of the stage is done with:

- easy-to-use Windows interface
- LabVIEW interface program (compiled program or source)
- MATLAB interface script
- C++ and Python libraries

<sup>\*\*</sup> extension cables available or shorter cable on request







