



# **XLS-5** series

## Precise linear piezo stage with high force output

The XLS-5 series are precise linear stages driven by an ultrasonic piezo motor. These stages combine high-speed positioning with nanometre precision and generate a high force output within a small volume. Xeryon's ultrasonic piezo motor ensures you a long lifetime, noiseless and vibration-free operation. In addition, the self-locking piezo motor holds the position of the stage when powered off. The reduced heat dissipation leads to a very stable nano-positioning system. The XLS-5 is used in metrology applications, e.g. for part alignment or sample manipulation. The XLS-5 series is available in different lengths and are easily stacked into an XY- or XYZ-assembly.

#### **Key features**

drive principle	patented Crossfixx™ ultrasonic piezo technology
bearings	precision crossed-roller
lifetime distance	> 1000 km / typ. 20 million cycles
control principle	closed-loop or open-loop position control
input voltage	48 V

#### Model code structure

stage type	stage	encoder	optional					
	length (mm)	resolution (nm)	vacuum compatibility	low- or non-magnetic bearings	short cage for increased stroke			
	-OPEI	-OPEN	-HV (10-6 mbar)					
		-1250						
	-40	-312						
		-78						
		-5						
XLS-5		-1		-LM / -NM	-SC			
	-60		-UHV (10-9 mbar)					
	-80	-80 same as for						
	-100 XLS-5-40	XLS-5-40						
	-120							

## **Environmental compatibility**

temperature range	-30°C to +70°C
humidity range	20% to 90% RH (non-condensing)
heat dissipation (motor only)	< 5 W
mounting surface flatness	< flatness specification of stage
Internal operation voltage	< 60 V

## **Motion performance**

	XLS-5 all lengths							unit	tole-	
	resolution			-1250	-312	-78	-5	-1		rance
		type	NA <sup>1</sup>	optical, incremental						
DER		grating period	NA <sup>1</sup>	79.8			20		μm	
ENCODER		resolution	NA <sup>1</sup>	1250	312	78	5	1	nm	
ū		index	NA <sup>1</sup>		1 p	er full strol	ке			
		accuracy	NA <sup>1</sup>	± 10	± 5		± 1		μm	typ.
	positioning	resolution = min. step size = min. incremental motion (MIM)	50000²	1250	350	80	25		nm	typ.
		unidirectional repeatability	± 50000 <sup>2</sup>	± 1250	± 350	± 80	± 25		nm	typ.
		bidirectional repeatability	± 50000 <sup>2</sup>	± 2500	± 700	± 160	± 50		nm	typ.
		max. speed (for -HV/-UHV)	500	50		50	25	mm/s	typ.	
STAGE		max. speed	1000	200		150	25	mm/s	typ.	
ST/		min. speed	5000 <sup>3</sup>		5		2	1	μm/s	typ.
	pəəds	stability (at typical speed of 10 mm/s)	± 10			± 1			%	typ.
	ods	point-to-point positioning 0 g load time for a 1 mm step <sup>4</sup> 100 g load	NA	2		80 120	25 45		msec msec	typ.
		point-to-point positioning time 10 mm 1 mm 100 µm	NA	13 2 2	5	170 80 50	50 25 15	0	msec msec msec	typ.
		operation duty cycle (for -HV/-UHV only)			50				%	max.
		operation duty cycle (for -mv/-OHV only)	120			1				max.

<sup>&</sup>lt;sup>1</sup> a closed-loop control can be achieved by connecting an external position encoder to the controller

Note: a detailed description of the technical terms used in this datasheet can be found on the Terminology page of our website.

## **Mechanical properties**

		XLS-5 -40	XLS-5 -60	XLS-5 -80	XLS-5 -100	XLS-5 -120	unit	tolerance
	length	40	60	80	100	120		
dimensions	width		47.6					
	height	16.8						
stroke/	standard cage	25	40	50	75	100		± 0.1
travel range	short cage (-SC)	30	48	69	85	109	mm	
max. acceleration		100	60	55	45	40	mm/s <sup>2</sup>	typ.
mass (w/o connector)		81	120	161	201	241	g	± 5%
load capacity (pay	/load limitation)	2						max.
	vertical	396	633	792	990	1188	N Nm	
load capacity*	lateral	396	633	792	990	1188		
(bearing force	tilt around pitch axis	1.50	2.25	3.00	3.75	4.50		max.
limitation)	tilt around yaw axis	1.50	2.25	3.00	3.75	4.50		
	tilt around roll axis	7.74	12.38	15.48	19.35	23.23		
driving force				5			N	min.
holding force		5						min.
passive holding s	tiffness			1			N/µm	typ.

<sup>&</sup>lt;sup>2</sup> when using stage in burst mode (50µm bursts)

<sup>&</sup>lt;sup>3</sup> lower average speeds can be achieved when using burst mode

<sup>&</sup>lt;sup>4</sup> settling within bidirectional repeatability range

stage material slider/base bearings		aluminium stainless steel		
cable length**		1.5	m	± 0.1
connector (stage to controller)		1x 15-pin D-sub HD male (standard) 1x 15-pin D-sub female (-HV)		

<sup>\*</sup> valid for stages with standard cage

<sup>\*\*</sup> extension cables available or shorter cable on request

#### **Error motion**

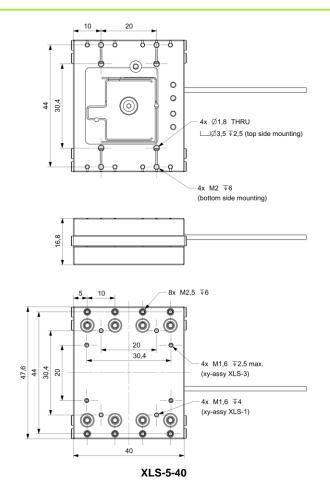
		XLS- length 40	-	XLS length 80				
resolution		-1250 -312	-78 -5 -1	-1250 -312	-78 -5 -1	unit	tolerance	
	straightness	± 5	±1	± 10	± 2	μm	max.	
	flatness	± 5	± 1	± 10	± 2	μm	max.	
error motion	pitch	120 25	24 5	120 25	24 5	µrad arcsec	max.	
error i	roll	120 25	24 5	120 25	24 5	µrad arcsec	max.	
	yaw	60 12.5	12 2.5	60 12.5	12 2.5	µrad arcsec	max.	

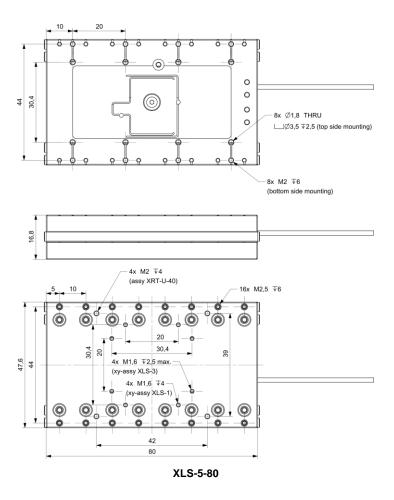
### Controller/software

The XLS-5 series linear stages are compatible with all Xeryon controllers. Controlling of the stage is done with:

- Easy-to-use Windows interface
- LabVIEW interface program (compiled program or source)
- MATLAB interface script
- C++ and Python libraries

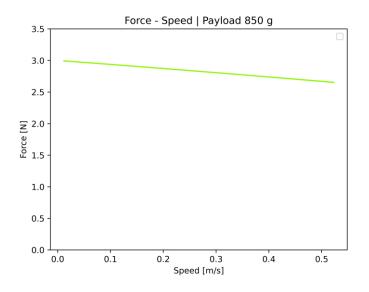
## Drawings (STEP-files are available on our website)



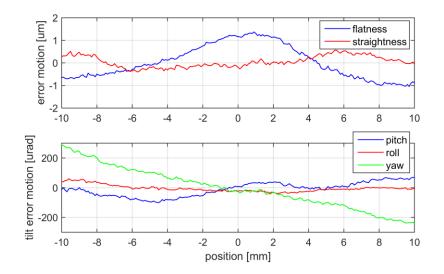


Note: stages XLS-5-50, XLS-5-60, XLS-5-70, XLS-5-100 and XLS-5-120 have similar mounting holes as shown in the drawings above.

#### Measurement data



Typical force-speed diagram of an XLS-5 stage with a payload of 850g.



Typical error motion values measured on an XLS-5-40 stage.

Last updated:4/03/2024. All specifications are subject to change without prior notice.